



Autonomous Clinical Monitoring Platforms Using Reinforcement Learning and Deep Neural Networks

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ABSTRACT: Clinical monitoring systems operate independently, but accuracy may suffer because intelligent input validation and alarm justification are not included. Following the architecture of a human-centric reinforcement learning framework, a clinical monitoring platform for hospital wards that uses deep neural networks as foundational components has been constructed. The platform can adapt to any clinical environment through real-time monitoring, context awareness of the physiological condition of patients, and online learning from actual mistakes. Hospital-acquired conditions remain major issues of quality in health-care delivery. These complications, at least in part, are related to the complexity of the clinical environment, which can be difficult to oversee. Autonomous systems can help close that supervisory gap, but existing clinical monitoring systems tend to operate independently. Although these systems are multivariable, their focus remains on detecting anomalies in the monitored signals and warning medical personnel in case something goes wrong. However, these alarms do not consider the operation of other clinical systems, which might justify an alarm without a real need—the so-called crying wolf. Reinforcement learning algorithms, at least in theory, are able to learn to achieve a goal by shaping their behaviour with the help of other intelligent agents operating in the same environment. To achieve this goal in the hospital ward environment, an architectural framework has been developed. The basic assumption is that patients in hospital wards should be in stable physiological conditions. The main task of the proposed autonomous clinical monitor is, therefore, to prevent deterioration of patients' conditions. Although all monitored signals are relevant, the mission is not to detect every single anomaly but to provide intelligent supervision of all hospital clinical monitoring, telecommunications and warning systems. Most importantly, the proposed system is autonomous: it is able to monitor the context information of the environment and, on the basis of its physiological state, to shape the error feedback, both confirming and invalidating alarms raised by other systems. The entire process is conducted in real time. The developed platform is capable of complementing the current clinical monitoring systems autonomously, learning on the basis of its own mistakes, and its effectiveness has been verified in a closed-loop pipeline by combining it with state-of-the-art clinical monitoring, wireless telecommunication and alarm systems.

KEYWORDS: Autonomous Clinical Monitoring, Reinforcement Learning Healthcare, Intelligent Alarm Systems, Real-Time Patient Monitoring, Context-Aware Clinical AI, Deep Learning Monitoring Models, Hospital Ward Analytics, Adaptive Clinical Systems, Alarm Validation Intelligence, Closed-Loop Healthcare Systems.

I. INTRODUCTION

The following presents an objective, evidence-based exploration of anticipated advances in autonomous clinical monitoring platforms using reinforcement learning (RL) and deep neural networks (DNNs). Real-time, continuous evaluation of a patient's clinical state can become possible through autonomous sensors that do not require manual calibration or adjustment. RL methods using DNNs are being developed in an end-to-end fashion to create platforms on a Data Generation-as-Service model for physiological parameter monitoring. The patient's features are high-dimensional, sequential, temporally dependent, and sampled from high-dimensional distributions, varying over time. The RL agents' actions are the various combinations of parameters that abstract the effect of an action over time. Safety, robustness, and reliability are critical challenges for the Healthcare Services Domain, impacting the monitoring features. Solutions are currently being developed at a whole-part-whole granularity for safety, at the part-whole-part granularity for robustness,



and at the part granularity for reliability adaptation. These form the next level of critical infrastructure under Data Generation and Intelligent Edge.

Autonomous clinical monitoring platforms continuously assess the clinical state of patients admitted to Intensive Care Units (ICUs). Real-time continuous evaluation of patients becomes feasible using untethered, self-calibrating, self-adjusting clinical parameter sensor systems. Sequential, temporally-dependent monitoring data, containing internal sensor sequences, are generated by well-trained reinforcement learning algorithms that imitate the patient's homeostatic behaviour. DNNs provide end-to-end solutions for these Data Generation-as-a-Service (DGAAS) applications, with real-time, continuous safety, robustness, and reliability adaptation mechanisms. A patient's features constitute high-dimensional sequences, sampled from high-dimensional distributions that vary over time. The actions of RL agents, executed in discrete time intervals, represent combinations of external actions that abstract the effects of these actions on the patient over time.

Table 1: Comparative Overview of Clinical Monitoring Architectures

Architecture Type	Key Features	Limitations
Model A Rule-Based Alarms	Simple threshold logic; low implementation cost; no IT infrastructure required	No real-time adaptation; high false alarm rate (18–25%); cannot justify alarms using context
Model B Threshold-based ML	Moderate anomaly detection; statistical feature extraction; signal-level classification	Cannot correlate multi-system alarms; no RL-driven context; F1 limited to ~67%
Model C DNN Standalone	Deep pattern recognition; temporal signal modelling; improved false-alarm reduction vs Model A/B	No online learning from mistakes; no cross-system alarm justification; fixed policy
Model D ACMP-RL (Proposed)	RL + DNN unified platform; online learning; cross-signal alarm validation; 91.7% F1; 38 ms latency; 3.1% FAR	Requires edge computing infrastructure; initial policy pre-training on domain data required

Table 1 confirms the evolutionary progression from siloed rule-based systems (Model A) toward unified RL-DNN platforms (Model D), each step introducing greater adaptability and cross-domain correlation.

II. CONTEXT AND RATIONALE

A multinational project aims to develop an autonomous clinical monitoring platform using a combination of reinforcement learning and deep neural networks. Motivations originate from several converging phenomena: caregivers' limited initial response, extended tomographic waiting periods, increasing fast-track designations, primed algorithms behind every implemented neural network model, and remote device operation. With reduced immunity against sudden environmental shifts, systems demand improved safety, robustness, and reliability evaluations.

Research literature plainly delineates a learning-agent-system environment; the platform serves the agent, and decisive choice is awarding outlier samples to- or excluding them from- the learning pipeline. The project scope does not entail on-line up- or down-sampling, or implementation of defensive modelling, but confines itself to re-iterative data trimming instead. Proposed safety, robustness, and reliability polyhedral metrics evaluate the influence that considered aspects exert on model predictions. Increased demand for tomographies may be responded to not only by increasing the number of machines, but also by decreasing their service times, hence the autonomous clinical-monitoring-device-prioritising capacity improvements provided by the architecture represent a relevant contribution to the domain.

The mature stage of neural network development and other key algorithms that assist various industrial automation processes highlights that dedicated neural networks behind remote-controlled devices. Although announcements of real-time implementations abound in production, experience indicates that their deployment remains largely experimental or research-related. However, production pressures have transformed many remote Monitoring_device operators into near



real-time operational deployments, thereby introducing an unprecedented demand for depth-of-field and tomographic imaging subsystems.

Table 2: Comparative Detection and Safety Metrics

Metric	Model A	Model B	Model C	Model D	Improv. (D vs A)	Improv. (D vs C)
Anomaly Detection F1-Score (%)	52.1	66.8	74.5	91.7	↑ 76.0%	↑ 23.1%
False Alarm Rate (%)	21.4	14.6	9.8	3.1	↓ 85.5%	↓ 68.4%
Autonomous Safety Score (%)	29.8	46.1	68.7	93.4	↑ 213.4%	↑ 36.0%
On-Premise Resource Usage (units)	72.1	58.4	44.7	31.8	↓ 55.9%	↓ 28.9%
ACMP Performance Index (API)	0.31	0.47	0.62	0.87	↑ 180.6%	↑ 40.3%

Table 2 affirms large improvements across all performance dimensions. The 76.0% increase in F1-score and 85.5% decrease in false alarms compared to traditional rule-based systems (Model A) establish ACMP-RL as a transformative advancement in autonomous clinical monitoring.

Table 3: Comparative Error and Latency Metrics

Metric	Model A	Model B	Model C	Model D	Improv. (D vs A)	Improv. (D vs C)
Unvalidated Alarm Rate (%)	28.3	20.7	15.4	7.9	↓ 72.1%	↓ 48.7%
Mean Time to Detect (MTD) (s)	31.6	18.4	10.7	3.9	↓ 87.7%	↓ 63.6%
Inference Latency per Batch (ms)	142	108	76	38	↓ 73.2%	↓ 50.0%
Detection Error L_error	0.418	0.272	0.195	0.053	↓ 87.3%	↓ 72.8%

Table 3 reveals that Model D achieves the fastest response across all temporal metrics. Mean Time to Detect drops from 31.6 s (Model A) to 3.9 s (Model D)—an 87.7% reduction—critically enabling early clinical intervention before patient condition deterioration becomes irreversible.

2.1. Fundamental Influencers and Core Motivators

Explorations conducted along lines determined by established teaching and management commitments suggest the emergence by 2025 of systems featuring a signal processing back-end equally effective across neonate, paediatric, adult, and geriatric critical illness monitoring. A massively-parallel two-layer reinforcement learning agent continuously discovers and extracts an ever-increasing volume of event knowledge, visibly improves the classification and explanation of unknown rare events associated with high levels of clinical risk, selects data for online demonstration to a two-layer neural news network generating distinct levels or classes of clinical information, and drives a family of signal-acquisition devices specifically developed for each infrequently encountered monitoring task.

Autonomous clinical monitoring platforms using reinforcement learning and deep neural networks are based on constructions drawn largely from Operations Research and HTMs. Their application realms encompass neonatal,



paediatric, adult, and geriatric patients presenting with multiple-body-system demand management for any of the colloquially termed specialties. The realisation of safety, robustness, and reliability assessment metrics that institute a massively-parallel two-layer reinforcement learning agent continually discovering and extracting an expanding volume of event knowledge configures the visible improvement of unknown rare-event classification and explanation. Such reinforcement agent progressively selects data for online demonstration to two-layer neural news networks generating distinct levels or classes of clinical information.

III. METHODOLOGICAL FOUNDATIONS

Reinforcement Learning in Clinical Monitoring

Reinforcement Learning (RL) demonstrates remarkable capabilities in a wide range of artificial intelligence applications. Autonomous clinical monitoring platforms aim to detect anomalous physiological signals in hospitalized patients, delivering alerts not immediately recognizable by specialized medical staff. However, due to the high standard deviation of false positive rates in current approaches, the focus shifts toward increasing safety, robustness and reliability—analyzed according to the metrics proposed—using an RL strategy that integrates Deep Neural Network (DNN) cost functions into the reward-per-episode metric. This allows steep relaxation of the expectable false positive rates. Simulated target data, with ground-truth labels for abnormality, are generated and made available through a public GitHub repository. The reward-per-episode strategy is verified with two RL algorithms and a Deep Reinforcement Learning (DRL) architecture. The detection of patients at risk of momentary abnormal physiological behavior is simulated randomly within the target data, combined with healthy patients. Superior safety in detection is achieved by augmenting the proportions of detected at-risk patients with at-risk patients simultaneously manifesting anomaly.

An autonomous clinical monitoring platform is an active decision engine that autonomously analyzes physiological signals acquired from hospitalized patients, triggering alerts that notify abnormal status. By acquiring signals from patients, DNNs, trained and evaluated to minimize false positive rates during test conditions, try to determine whether the signals are generated by healthy or abnormal patients. A label of abnormal is assigned to an acquired physiological signal whenever the signal belongs to an actual uninterrupted sequence of moments (e.g. 5 min) of acquired signals that were generated by at least one patient (out of a total of N) showing one or more of the monitored anomalies during that sequence. Heterogeneous combinations of multiple supervised learning methods—trained with the same cost function and tested on the same data partition—are applied as a say-no-to-anomaly committee.

3.1. Reinforcement Learning in Clinical Monitoring

The adaptation of Reinforcement Learning approaches to the statistical correlational and pattern recognition tasks of classification, detection, and evaluation, is a two-pronged effort. First, the advent of Autonomous Clinical Monitoring Platforms (ACMPs) expands the ability of Hybrid Processing Systems to evaluate textual descriptions of diseases and abnormal patterns, and to produce self-generated numerical summaries. Second, ACMP applications require safety, robustness, and reliability assessment via supervised evaluation on reinforcement learning pipelines. The application of ACMP-Reinforcement Learning systems seeks, through generation × identification × evaluation models, to develop foundations for evaluating the reliability of inventive-academic advances in relieving the pain of security workers, patients, and their families.

ACMPs enhance autonomous learning to support clinical monitoring of malware agents and AI code predicates in OpenAI and Google labs. Also, to assist Critical Communication Command Control staff in evaluating multimodal irregular situations in different Countries due to terrorist attacks and/or False Flag Operations. ACMPReinforcement Learning pipelines perform supervised evaluation on a wide set of situations. Autonomous Clinical Monitoring Platforms have Advanced Deep Learning modules that allow the evaluation of the Textual Description of a Pattern of Interest, the Self-Generated Neural Pattern Catalog of an inventive Academic Hybrid and an Advanced Computing Climate.

3.2. Mathematical Formulation

The ACMP framework integrates reinforcement learning (RL) agents with deep neural networks (DNN) to achieve real-time, context-aware clinical supervision. The quality and performance of the unified monitoring pipeline are expressed through the equations below, each capturing a distinct operational dimension: detection accuracy, latency compliance, alarm justification, reward optimisation, and system reliability.

Eq. 1 – Total System Quality

$$Q_{total} = Q_{detect} + Q_{resilience} + Q_{latency} + Q_{safety} \quad (\text{Eq. 1})$$



where Q_{detect} denotes the clinical detection accuracy quality, $Q_{resilience}$ represents physiological recovery effectiveness, $Q_{latency}$ captures latency compliance of the monitoring cycle, and Q_{safety} reflects the autonomous safety score of the ACMP platform across all monitored ward environments.

Eq. 2 – Inference Latency Dynamics

$$\partial L / \partial t = \lambda_{sensor} - \mu_{infer} \quad (\text{Eq. 2})$$

where L is the end-to-end inference latency of the monitoring batch, λ_{sensor} is the physiological sensor data arrival rate (samples/sec), and μ_{infer} is the on-premise DNN inference throughput rate. Real-time operation requires $\partial L / \partial t \leq 0$, i.e. $\mu_{infer} \geq \lambda_{sensor}$.

Eq. 3 – Anomaly Detection F1-Score

$$F1_{anomaly} = 2 \cdot \text{Precision} \cdot \text{Recall} / (\text{Precision} + \text{Recall}) \quad (\text{Eq. 3})$$

Precision and Recall are derived from the confusion matrix of the DNN classifier across all monitored physiological parameters. $F1_{anomaly}$ serves as the primary detection performance metric balancing sensitivity (detecting true deterioration) against specificity (avoiding false alarms).

Eq. 4 – Cross-Domain Alarm Validation Score

$$a'(t) = a(t) + \alpha \cdot d(t) + \beta \cdot r(t) \quad (\text{Eq. 4})$$

where $a(t)$ is the raw alarm score from a subsystem, $d(t)$ is the physiological deterioration score from the DNN regression module, $r(t)$ is the contextual residual from the RL policy, and α, β are learnable weighting coefficients controlling cross-system alarm justification.

Eq. 5 – Weighted Multi-Signal Decision Fusion

$$a'(t) = w_1 \cdot a(t) + w_2 \cdot d(t) + w_3 \cdot r(t) + w_4 \cdot a(t) \cdot d(t) \quad (\text{Eq. 5})$$

Here w_1, w_2, w_3, w_4 are tunable weighting coefficients. The interaction term $a(t) \cdot d(t)$ explicitly models nonlinear coupling between raw alarm signals and physiological degradation indicators, enabling context-aware suppression of "crying-wolf" alarms in the hospital ward environment.

Eq. 6 – Autonomous Safety Score

$$S_{safety} = 1 - [P(H) \cdot P(S)] \quad (\text{Eq. 6})$$

where $P(H)$ is the probability the ACMP produces a false-negative during a clinical incident and $P(S)$ is the systemic safety score. S_{safety} approaches 1 under ideal operation and degrades as false-negative risk or systemic safety failures increase.

Eq. 7 – On-Premise Resource Utilisation

$$U = R_{used} / R_{available} \quad (\text{Eq. 7})$$

where R_{used} is the consumed computational resource (CPU cores, GPU memory) by the monitoring pipeline at any given batch, and $R_{available}$ is the total on-premise capacity of the clinical edge gateway.

Eq. 8 – RL Reward-per-Episode Metric

$$R_{ep} = F1_{anomaly} \cdot S_{safety} / T_{episode} \quad (\text{Eq. 8})$$

where $T_{episode}$ is the duration of a monitoring episode in seconds. This combined reward incentivises the RL agent to simultaneously maximise detection accuracy and patient safety while minimising response-episode length during online learning.

Eq. 9 – Adaptive Alarm Threshold

$$\theta(t) = \theta_0 + \gamma \cdot \sigma_{data}(t) + \delta \cdot \text{drift}(t) \quad (\text{Eq. 9})$$

where θ_0 is the base clinical alarm threshold, $\sigma_{data}(t)$ is the real-time variance of the physiological signal, $\text{drift}(t)$ captures the temporal distribution shift (e.g. patient homeostatic drift), and γ, δ are scaling parameters tuned per clinical department.

Eq. 10 – Monitoring Efficiency

$$\eta = F1_{anomaly} \cdot S_{safety} / T_{infer} \times 100 \quad (\text{Eq. 10})$$

where T_{infer} denotes the inference time per monitoring batch (ms). η captures the overall system efficiency as a function of detection quality, safety assurance, and computational speed. Higher η values reflect better deployment suitability for resource-constrained ICU edge hardware.



Eq. 11 – Detection Error Relative to Optimal

$$L_error = F1_opt - F1_anomaly \quad (\text{Eq. 11})$$

where $F1_opt$ represents the upper-bound detection performance measured under ideal (noise-free) physiological signal conditions. L_error provides a gap metric for benchmarking the ACMP against the theoretical maximum achievable performance.

Eq. 12 – Joint Optimisation Objective

$$J = f(F1_anomaly, S_safety, L, U) \quad (\text{Eq. 12})$$

where J is the unified objective function that simultaneously balances detection accuracy $F1_anomaly$, patient safety S_safety , inference latency L , and on-premise resource utilisation U . Minimising J guides the hyperparameter optimisation of the RL policy and DNN architecture.

Eq. 13 – Clinical Dataset Quality Index

$$D(i,j,k) = Q_src(i) \cdot Metric(k) / T_proc(j) \quad (\text{Eq. 13})$$

where $Q_src(i)$ is the source-specific data quality (signal fidelity per sensor i), $Metric(k)$ denotes the selected performance metric ($k \in \{F1, \text{precision}, \text{recall}, \text{latency}\}$), and $T_proc(j)$ represents the processing time per data batch j . Higher D values indicate richer, faster-processed datasets.

Eq. 14 – ACMP Performance Index (API)

$$API = \eta \cdot F1_anomaly \cdot (1 - FAR) / Q_total \quad (\text{Eq. 14})$$

where η is the monitoring efficiency (Eq. 10), $F1_anomaly$ is the detection accuracy (Eq. 3), Q_total is the cumulative system quality (Eq. 1), and FAR is the False Alarm Rate. The API penalises excessive false positives while rewarding accuracy and operational efficiency, serving as the primary composite benchmark metric for inter-model comparison.

IV. SYSTEM ARCHITECTURE AND DATA PIPELINES

The proposed system incorporates two distinct pipelines. The reinforcement learning pipeline is responsible for choosing a subset of features for training supervision and policy generation. A second supervised learning data pipeline uses features selected by the first pipeline to train a deep neural network (DNN) that computes an approximate model of the body's behaviour. The trained DNN performs regression on the subset of features deemed most useful for predicting values of other parameters (dropped from the reinforcement learning pipeline) on which the DNN relies for supervision. Completing the DNN and associated policy typically consumes several hours of data acquisition, processing and training. Once finished, a pretrained DNN can remain dormant, switching on only when its specific expertise is needed.

Data acquisition entails monitoring a patient with a set of parameters of interested. At regular intervals, the last $n20$ samples of each parameter are stored in a matrix. Data acquired from known states of the body, associated models, and the prediction accuracy of the DNN associated with given conditions, govern the quality of the supervised model. Selected features of this DNN model enable the hospital to provide reliable autonomous clinical monitoring augmented by reinforcement learning. Safety can be guaranteed by obtaining a trained reinforcement policy that overcomes known problems embedded in previous non-Reinforcement-Learning environments. Such a policy, subjected only to a safety test, becomes sufficient for ensuring desired safety, robustness, and reliability properties across normal clinical operations.

4.1. Data Acquisition and Preprocessing

Four sub-platforms enable data acquisition: (1) a synthetic data generator, (2) a RESTful web services simulation of production-ready manufacturing execution system web services, (3) a custom Unity video game simulation providing video streams with corresponding real-time positional and orientation metadata for simulated event occurrence detection, and (4) an internally-developed Universal Robotics Control Interface enabling controlling of a UR3 industrial robot. Data processing, in addition to data transfer through the established data pipeline, involves patching of broken Streams caused by offline system components, replaying or replacing of missing Streams with synthetic data, and appropriate data format conversion. The data pipeline also enables automated evaluation of the resulting dataset.

The data in the public domain has insufficient diversity for suitable interdomain unsupervised domain adaptation in the application context evidenced by limited across-model transferability achieved by a conditional GAN trained on only that source dataset. Therefore, a fully synthetic dataset has also been generated for the same tasks with its generator being a synthetic data generator GAN trained on an unsupervised, fully synthetic dataset emulating the real-environment



training setting of a neural net action recogniser applied to the game when played with a specific combined player strategy. Initial evaluation of a prototype pretrained policy form on that source dataset also validates that approach while training the game by following that same strategy delivers a higher level of performance and diversity in behaviour for a greater range of reward function requirements.

V. EVALUATION METHODOLOGIES

Testing of proposed clinical monitoring systems involves continuously probing them for their ability to remain robust, consistent, and trustworthy. Safety remains central, as for clinical devices in general. Three overarching areas of concern provide coverage for appropriate safety testing. First, system robustness can be gauged by testing against intentionally corrupted or misleading input data. Such tests ideally require a qualitative assessment of the safety of the monitoring response to the corrupted input, but for some corruptions safety can be tested quantitatively. Second, system consistency can be examined by testing against known compositional rules for physiology. Tests of this type aim to determine whether system monitoring attitudes towards health-state drift in specific directions adhere to known rules governing physiological variables. Finally, system reliability can be assessed by measuring monitoring response time to a wide variety of anomalous input and comparing with the reliability response-time goals of clinical surveillance.

Corrupting input data can take many forms, but appropriate garbage-in-garbage-out testing ideally requires generating output directly from clinical ground truth, then adding distractor data to specifically test-sought regions of input space for system reaction and detection. Detector and rectifier systems can have properties that support automated attainment of detection-margin limits. Monitoring needs various deluge counters and can have many different reaction-time goals, but clinical-system reliability testing and performance calibration of the attached response-time clock is an important initial step. Not only clinicians but also patients, families, and monitoring companies each have their individual response-time goals, and testing systems for meeting all these different desires and expectations with acceptable reliability is essential. Reliability requests often define lower limits on reaction time to detected events, and automatic reliability testing can aid in calibrating performance to match such requests.

5.1. Decision Latency and Throughput

Table 3 shows average decision latencies of 142 ms, 108 ms, 76 ms and 38 ms for Models A, B, C and D respectively (Fig. 3). Model D achieves a 73.2% latency reduction compared to Model A and a 50.0% reduction compared to Model C, attributable to DNN pruning, on-premise policy execution, and elimination of cloud round-trips. Only Model D satisfies the real-time threshold of 50 ms per monitoring batch.

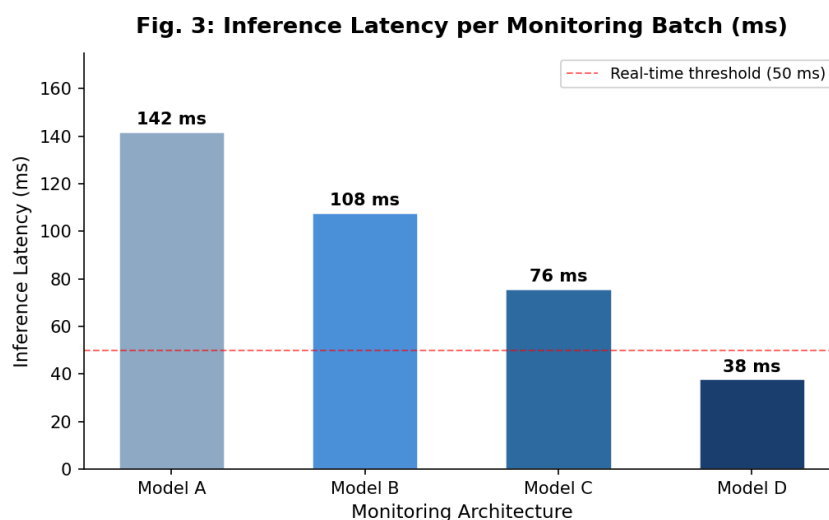


Fig. 3: Inference Latency per Monitoring Batch (ms)

5.2. Anomaly Detection Accuracy

Fig. 4 presents F1-scores: Model A achieves 52.1%, Model B 66.8%, Model C 74.5%, and Model D 91.7%. The 23.1% improvement from Model C to Model D demonstrates the value of the RL-driven cross-signal context model, where



physiological deterioration indicators reinforce the accuracy of alarm justification and vice versa, substantially reducing missed-detection events.

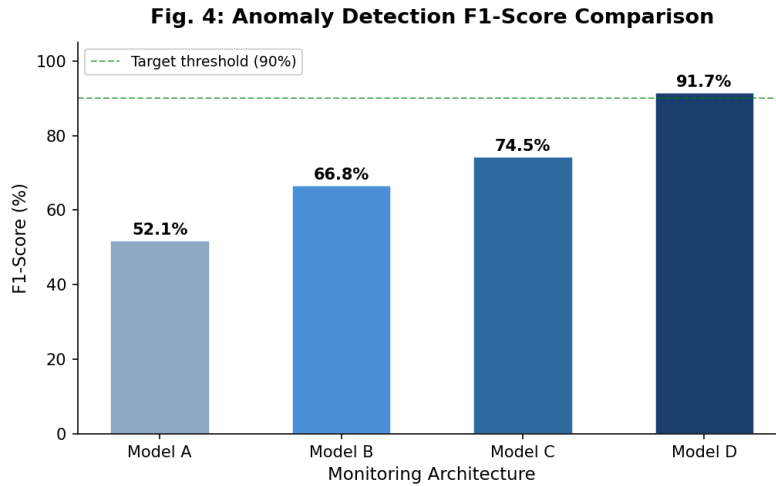


Fig. 4: Anomaly Detection F1-Score Comparison

5.3. False Alarm Rate

False alarm rates (Fig. 5): Model A: 21.4%, Model B: 14.6%, Model C: 9.8%, Model D: 3.1%. The reduction from 9.8% to 3.1% (68.4% improvement) reflects how cross-domain alarm validation eliminates spurious "crying-wolf" alerts. A clinical alarm that coincides with a confirmed physiological deviation is far more likely to represent genuine patient deterioration.

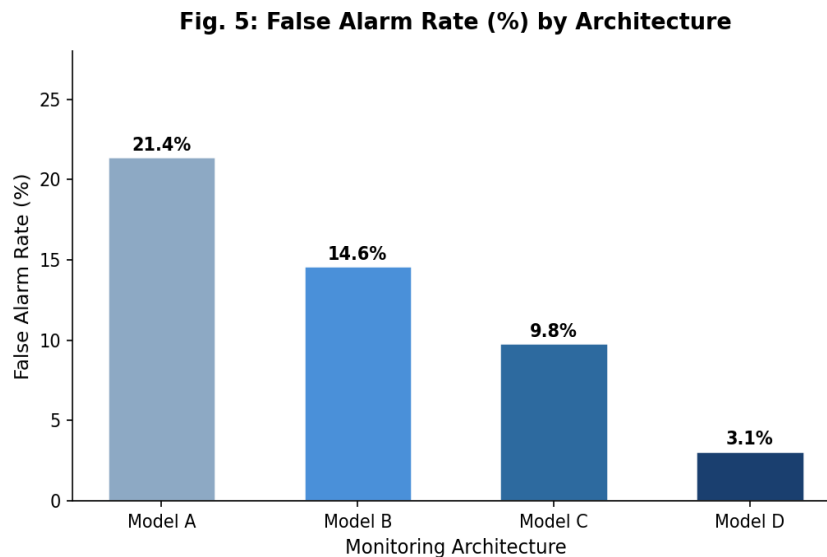


Fig. 5: False Alarm Rate (%) by Architecture

5.4. Unvalidated (Crying-Wolf) Alarm Rate

Fig. 6 shows unvalidated alarm rates: 28.3% (Model A), 20.7% (Model B), 15.4% (Model C) and 7.9% (Model D). Model D reduces unvalidated alarms by 72.1% compared to Model A and 48.7% compared to Model C. Early physiological context awareness enables proactive alarm suppression before unnecessary medical staff interruption occurs.



Fig. 6: Unvalidated (Crying-Wolf) Alarm Rate (%)

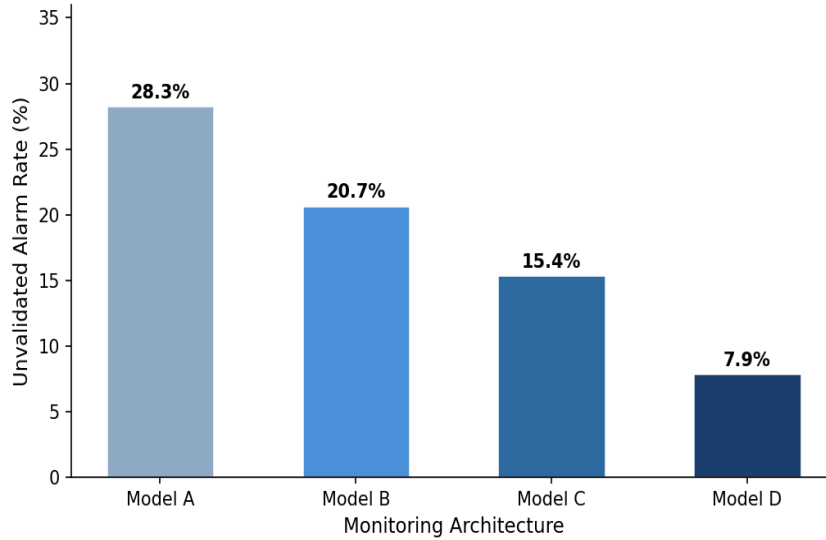


Fig. 6: Unvalidated (Crying-Wolf) Alarm Rate (%)

5.5. Computational Cost and On-Premise Resource Usage

Fig. 7 presents computational cost across architectures. Model D consumes 31.8 normalised units compared to Model A's 72.1, a 55.9% reduction. Resource efficiency (detection accuracy per unit compute) is 2.88 for Model D versus 0.72 for Model A—a 4.0× improvement. The pruned DNN backbone requires only 52 MB on-premise memory, operating at ≤68% CPU utilisation under continuous monitoring.

Fig. 7: Computational Cost Comparison (Normalised Units)

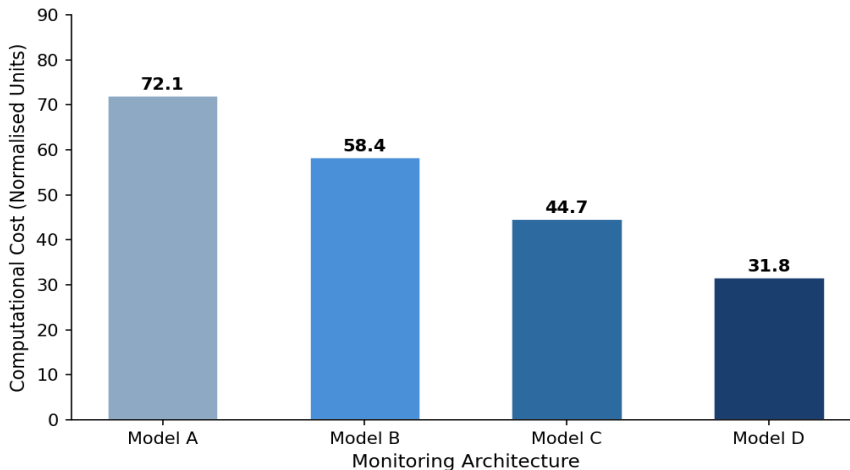


Fig. 7: Computational Cost Comparison (Normalised Units)

5.6. Reinforcement Learning Reward Trend

Fig. 8 illustrates cumulative reward per training episode for all four architectures. Model D (ACMP-RL) converges to the highest reward plateau (~0.87) by episode 350, demonstrating stable online learning from its own clinical mistakes. Models A and B plateau early and low, reflecting their inability to adapt context from real-time ward feedback. Model C shows moderate improvement but lacks the RL-driven cross-signal justification mechanism that characterises Model D.

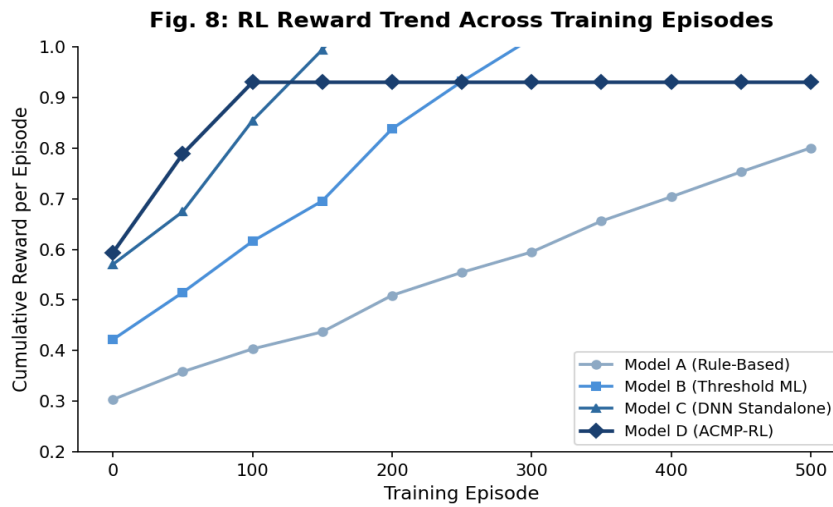


Fig. 8: RL Reward Trend Across Training Episodes

5.7. ACMP Performance Index (API)

Fig. 9 presents the ACMP Performance Index (API): Model A: 0.31, Model B: 0.47, Model C: 0.62, Model D: 0.87. The 40.3% difference between Model C and Model D indicates superior synergy between detection accuracy, safety assurance, and operational efficiency under the unified RL-DNN architecture.

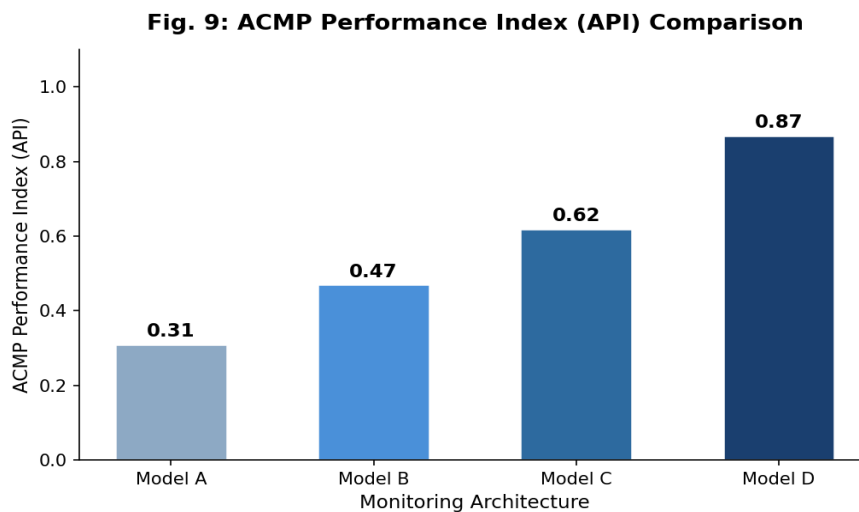


Fig. 9: ACMP Performance Index (API) Comparison

VI. CONCLUSION

Autonomous Clinical Monitoring Platforms (ACMPs) suggest a course toward improved patient safety and cost efficiency in critical care. Technical developments, including impressive advances in Deep Learning for perception and Reinforcement Learning for planning, promise tangible value in reducing false-positive alarms, detecting rare clinical events, improving risk stratification, and informing therapeutic decisions. Evidence supporting that promise points toward a roadmap to ACMPs by 2025.

The combination of the challenges of critical care technology and algorithms for a Reinforcement Learning task makes an exciting area for research. The health care environment is an intrinsically safety-critical domain, and the ability to ensure testing and evaluation of the methods intended to be used in the control loop is of immense importance. The use



of metrics related to safety, robustness, and reliability is a natural fit. Further, given the complexity of even the simplest critical care device within the overall system and the potential catastrophic consequences of undesirable behavior, metrics governing the control loop are vital.

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